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## Nexus Ultimate Prop Controller MQTT Integration Guide v1.2

This guide documents MQTT behavior for systems added from the web UI (Config -> Integrations -> Add Integration System -> mqtt).

### UI Add Defaults (MQTT)

When you add a new MQTT system from the UI, the stored defaults are:

- type: "mqtt"
- enabled: true
- base: ""
- subscribe\_cmd: true
- timeout\_ms: 2000
- rate\_limit\_ms: 0
- publish.events: true
- publish.inputs: true
- publish.analog: true
- publish.state: true
- publish.errors: true
- publish.actions: true
- publish.health: true

If base is blank, effective base is:

```
nexusPropControllers/{room_prefix}/props/{device_name}
```

### Default MQTT Input Address Map (What Firmware Listens To)

subscribe\_cmd=true is enabled by default, so command subscriptions are active.

### Subscription Filters

Case	Subscribed Topic Filter
Always (primary)	<effective_base>/cmd/#
Additional enabled MQTT systems with unique base	<system_base>/cmd/#

Notes: - If a system base is empty, it resolves to <effective\_base>. - If multiple systems resolve to the same base, that subscription is effectively the same filter. - Manual routes (integrations.manual\_routes with transport: "mqtt") are subscribed as explicit topics from manual\_routes.path and matched against full inbound topics (no base-prefix rewrite). - Outbound mqtt actions publish to the explicit configured target topic (no base-prefix rewrite).

### Inbound Command Mapping

All received command messages are accepted on subscribed . . . /cmd/# topics and then mapped as follows:

Match Rule	Topic Form	Payload Form	Result
Envelope payload (preferred)	Any subscribed .../cmd/... topic	<code>{"action":"...", "target":"...", "payload":...}</code>	<code>runAction(action, target, payload)</code>
Path encoded A	<code>.../cmd/action/&lt;action&gt;/&lt;target&gt;</code>	Raw payload string	<code>runAction(action, target, raw_payload)</code>
Path encoded B	<code>.../cmd/&lt;action&gt;/&lt;target&gt;</code>	Raw payload string	<code>runAction(action, target, raw_payload)</code>
Path encoded C	<code>.../api/action/&lt;action&gt;/&lt;target&gt;</code>	Raw payload string	<code>runAction(action, target, raw_payload)</code>
Legacy command-router payload	Any subscribed .../cmd/... topic	<code>{"cmd":"...", ...}</code>	Routed through legacy command router

## Explicit Examples

Topic	Payload	Runtime Interpretation
<code>&lt;base&gt;/cmd/action</code>	<code>{"action":"set_state","target":"armed","payload":1}</code>	set state to armed
<code>&lt;base&gt;/cmd/action/set_var/puzzle</code>	1	<code>set_var("puzzle", "1")</code>
<code>&lt;base&gt;/cmd/operator_control/Reset</code>	<code>'(empty)  operator_control("Reset","")   /cmd/relay/Solenoid trigger relay("Solenoid","trigger")   /cmd/anything {"cmd":"relay","id":"Solenoid","value":true}'</code>	legacy command-router relay command

## Default MQTT Output Address Map (What Firmware Publishes)

With default publish flags from UI add, these topics are published.

### Connect-Time Publications

Topic	Retain	Payload
<code>&lt;base&gt;/sys/online</code>	Yes	online
<code>&lt;base&gt;/sys/info</code>	Yes	JSON with firmware version
<code>&lt;room_prefix&gt;/&lt;device_name&gt;/online</code>	No	device IP string

For additional enabled MQTT systems with a different resolved base, `<sys_base>/sys/online` and `<sys_base>/sys/info` are mirrored too.

### Periodic Publications

Topic	Retain	Interval	Payload
<code>&lt;base&gt;/state</code>	Yes	~15s	state snapshot JSON
<code>&lt;base&gt;/sys/health</code>	No	~5s	health JSON (heap, uptime)

### Event Publications

Topic Pattern	Retain	Payload
<code>&lt;base&gt;/events/&lt;event_type&gt;</code>	No	event JSON/text payload

### Explicit Event Type List

These event type suffixes are emitted by firmware code paths:

- action
- actuator
- analog
- analog\_trigger
- color
- espnow\_event
- gesture

- i2c
- input
- input\_edge
- logic
- rfid
- rfid\_collection
- rfid\_data
- rfid\_recover
- rfid\_rule
- route
- sensor\_trigger
- sequence
- sequence\_learn
- system
- test

### Publish-Flag Routing Map

Event Type	Controlling Publish Flag
input	publish.inputs
analog	publish.analog
action, sequence	publish.actions
error (when emitted as an event type)	publish.errors
input_edge and all other listed event types	publish.events

Periodic/state channels (not events/<type> routing): - <base>/state uses publish.state. - <base>/sys/health uses publish.health.

### Scope Notes

- This guide is strictly for UI-added MQTT integrations.
- Manual routes can add additional behavior, but are not part of default UI-add behavior.